

## Mathematical Methods of Physics 116A- Winter 2018

### Physics 116A

#### Home Work # 5 Solutions

Posted on Feb 8, 2018

Due in Class Feb 15, 2018

#### §Required Problems: Each problem has 10 points

E.g. MB 19.16 means problem #16 on page 19 in the book by M. Boas, 3rd Edition.

1. MB 95.10 Show that a skew-symmetric matrix determinant of odd order is zero.

Using the notation  $\det(A)$  for the determinate of an  $n \times n$  matrix  $A$ , we can write a very compact proof:

$$\det(A) = \det(A^T) = \det(-A) = (-1)^n \det(A) .$$

We use the following properties:

- a)  $\det(A) = \det(A^T)$  (in general)
- b)  $A^T = -A$  (for a skew symmetric matrix)
- c)  $\det(-A) = (-1)^n \det(A)$  (The determinate of  $-A$  is the same as negating each row of the  $\det(A)$ ).

Hence, for  $n$  odd we have a contradiction  $\det(A) = -\det(A)$  unless  $\det(A) = 0$ .

2. MB 96.18

Find the solution of  $z$  using Cramer's rule given the following set of equations:

$$\begin{cases} (a-b)x - (a+b)y + 3b^2z = 3ab \\ (a+2b)x - (a+2b)y - (3ab+3b^2)z = 3b^2 \\ bx + ay - (2b^2+a^2)z = 0 \end{cases} .$$

First we need compute the determinate

$$D = \begin{vmatrix} (a-b) & -(a-b) & 3b^2 \\ (a+2b) & -(a+2b) & -(3ab+3b^2) \\ b & a & (2b^2+a^2) \end{vmatrix} .$$

Add  $C_2$  to  $C_1$ :

$$D = \begin{vmatrix} 0 & -(a-b) & 3b^2 \\ 0 & -(a+2b) & -(3ab+3b^2) \\ a+b & a & (2b^2+a^2) \end{vmatrix} .$$

Do a Laplace development of  $C_1$ :

$$D = (a + b) \begin{vmatrix} -(a - b) & 3b^2 \\ -(a + 2b) & -(3ab + 3b^2) \end{vmatrix}.$$

Pull  $3b$  out of  $C_2$  and compute the 2 determinate:

$$D = 3b(a + b) \begin{vmatrix} -(a - b) & b \\ b & -(a + b) \end{vmatrix} = 3b(a + b)(a^2 + ab + b^2).$$

Next, we use Cramer's rule to find  $z$ ,

$$z = \frac{1}{D} \begin{vmatrix} (a - b) & -(a - b) & 3ab \\ (a + 2b) & -(a + 2b) & 3b^2 \\ b & a & 0 \end{vmatrix}$$

where the determinate in the numerator is found by replacing the coefficients for  $z$  with the coefficients of the solution. Add  $C_1$  to  $C_2$ :

$$\begin{vmatrix} 0 & -(a - b) & 3ab \\ 0 & -(a + 2b) & 3b^2 \\ a + b & a & 0 \end{vmatrix}.$$

Do a Laplace development of  $C_1$ :

$$(a + b)/D \begin{vmatrix} -(a - b) & 3ab \\ -(a + 2b) & 3b^2 \end{vmatrix}.$$

Pull  $3b$  out of  $C_2$ :

$$3b(a + b)/D \begin{vmatrix} -(a - b) & a \\ -(a + 2b) & b \end{vmatrix}.$$

Pull  $3b$  out of  $C_2$  and compute the determinate:

$$3b(a + b)/D \begin{vmatrix} -(a - b) & a \\ -(a + 2b) & b \end{vmatrix} = 3b(a + b)(a^2 + ab + b^2)/D = 1.$$

3. MB 112.20 Find the equation of a plane that passes through the points  $P(0, 1, 1)$ ,  $Q(2, 1, 3)$ , and  $R(4, 2, 1)$ .

For every plane there exist a vector normal to all vectors in the plane which we call  $\vec{N}$ . We can compute the normal vector by taking the cross product of any two vectors non-parallel vectors that lie in the plane. Note that the vectors that joins points  $P$ ,  $Q$ , or  $R$  lies in the plane. Two such vectors are  $\vec{PQ} = (2, 0, 2)$  and  $\vec{PR} = (4, 1, 0)$ . The cross product is

$$\vec{N} = \vec{PQ} \times \vec{PR} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 2 & 0 & 2 \\ 4 & 1 & 0 \end{vmatrix} = -2\hat{x} + 8\hat{y} + 2\hat{z} = (-2, 8, 2).$$

If  $\vec{r} - \vec{r}_0$  defines an arbitrary vector in the plane, then

$$\vec{N} \cdot (\vec{r} - \vec{r}_0) = 0$$

since the normal vector is perpendicular to any vector in the plane. So if we let  $\vec{r}_0 = \vec{PO} = (0, 1, 1)$  where  $O(0, 0, 0)$  is the origin and  $\vec{r} = (x, y, z)$  we have

$$\vec{N} \cdot (\vec{r} - \vec{r}_0) = -2(x - 0) + 8(y - 1) + 2(z - 1) = 0.$$

Hence,

$$\boxed{x - 4y - z + 5 = 0}.$$

4. MB 112.22 Find the angle between the two planes

$$\begin{cases} 2x - y - z = 4 \\ 3x - 2y - 6z = 7 \end{cases}.$$

The angle between two planes is equivalent to the angle between the normal vectors of the two planes. We can find the norm of the first plane,  $\vec{N}_1 = (2, -1, -1)$ , by reading off the coefficients. Similarly for the second equation, we find  $\vec{N}_2 = (3, -2, -6)$ . The dot product of the norms is defined at

$$\vec{N}_1 \cdot \vec{N}_2 = |\vec{N}_1| |\vec{N}_2| \cos \theta,$$

where  $|\vec{N}_1| = \sqrt{6}$  and  $|\vec{N}_2| = \sqrt{7}$ . Thus

$$\boxed{\cos \theta = \frac{2}{\sqrt{6}}}.$$

5. MB 113.31 Find the distance from  $P(-2, 4, 5)$  to the plane  $2x + 6y - 3z = 10$ .

We can find the distance from a point to a plane by defining the vector  $\vec{QP}$  to be an arbitrary point  $Q(x, y, z)$  on the plane to the point  $P$  and projecting that on to the normalized normal vector of the plane. The normal vector of the plane  $\vec{N} = (2, 6, -3)$  and  $|\vec{N}| = 7$ . The distance is defined at

$$|\hat{N} \cdot \vec{QP}| = \boxed{\frac{5}{7}}$$

6. MB 113.27 Find the plane that passes through  $P(2, 3, -2)$  and is perpendicular to the planes

$$\begin{cases} 2x + 6y - 3z = 10 \\ 5x + 2y - z = 12 \end{cases}.$$

The orientation of a normal vector of a plane that is perpendicular to two other planes is defined by the cross product of the normal vectors of two other planes. In our case we let  $\vec{A} = (2, 6, -3)$  be the normal vector of the first plane and  $\vec{B} = (5, 2, -1)$  be the normal vector of the second plane. The cross product gives the normal vector of our plane

$$\vec{C} = \vec{A} \times \vec{B} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ 2 & 6 & -3 \\ 5 & 2 & -1 \end{vmatrix} = 0\hat{x} - 13\hat{y} - 26\hat{z} = (0, -13, -26) .$$

The equation of a plane is given by

$$\vec{C} \cdot (\vec{r} - \vec{r}_0) = 0(x - 2) - 13(y - 3) - 26(z + 2) = 0 ,$$

where  $\vec{r}_0 = (2, 3, -2)$ . This simplifies to

$$\boxed{y + 2z + 1 = 0} .$$