

# Mathematical Methods of Physics

Physics 116B- Spring 2018

Midterm Examination, Total 100 Points

May 3, 2018

Your Name (Capitals) .....

- Please use only the scratch paper for your answers. DO NOT write anything on the question paper except your name.
- Show details of the work and box the final results.
- Answers without detailed working will not be receive any score.
- One page of notes with formulas is allowed.
- No calculators or cell phone usage please.

1. Find the four independent *real* solutions of the linear differential equation

$$(D + 1)^2(D^2 + 4)y = 0.$$

The result should be expressed in terms of 4 real parameters. ... [25]

*Solution: The auxiliary polynomial is factorized as  $(d+1)^2(d+2i)(d-2i)$ . We have a double root at  $d = 1$  and single roots everywhere else. We can write the answer by inspection*

$$y = A \sin(2t + \phi) + (B + Ct)e^{-t}$$

2. Given four 3-dimensional vectors  $\vec{X}, \vec{Y}, \vec{P}, \vec{Q}$  calculate

$$\epsilon_{ijk}\epsilon_{imn}X_jY_kP_mQ_n,$$

where  $\epsilon_{ijk}$  is the Levi-Civita tensor. ... [10]

*Solution: This is a simple application of the formula  $\epsilon_{ijk}\epsilon_{imn} = \delta_{jm}\delta_{kn} - \delta_{jn}\delta_{km}$ . Applying this we get the result*

$$(\vec{X} \cdot \vec{P})(\vec{Y} \cdot \vec{Q}) - (\vec{X} \cdot \vec{Q})(\vec{Y} \cdot \vec{P})$$

3. The position vector of a moving particle moving on the surface of a cylinder, is given in terms of the three unit cartesian vectors as

$$d\vec{s} = \hat{i}dx + \hat{j}dy + \hat{k}dz.$$

We make a change of variables to cylindrical coordinates  $x = r \cos(\theta)$ ,  $y = r \sin(\theta)$ ,  $z$ , and note that constraint implies  $\dot{r} = 0$ . Using this constraint find the velocity

$$\vec{v} = \frac{d\vec{s}}{dt}$$

and acceleration

$$\vec{a} = \frac{d^2\vec{s}}{dt^2}$$

in terms of the vectors  $\hat{e}_\theta$ ,  $\hat{e}_r$ ,  $\hat{z}$ , and the derivatives of  $\theta$ ,  $z$ .

In the special case where the rates of change  $\dot{\theta}$  and  $\dot{z}$  are constant, show that the particle acceleration is non-zero and centripetal (i.e. along the radial direction). ... [35]

*Solution: We can write*

$$d\vec{s} = \hat{e}_r dr + r\hat{e}_\theta d\theta + \hat{z}dz,$$

*and hence dividing by dt*

$$\vec{v} = \hat{e}_r \dot{r} + r\hat{e}_\theta \dot{\theta} + \hat{z}\dot{z}.$$

*Using the constraint  $\dot{r} = 0$  we can drop the first term. To take one more derivative, we need*

$$\frac{d\hat{e}_r}{dt} = \hat{e}_\theta \frac{d\theta}{dt}, \quad \frac{d\hat{e}_\theta}{dt} = -\hat{e}_r \frac{d\theta}{dt}.$$

*With this we obtain*

$$\vec{a} = \frac{d^2\vec{s}}{dt^2} = r \left( \hat{e}_\theta \ddot{\theta} + \hat{e}_r (\dot{\theta})^2 \right) + \hat{z}\ddot{z}.$$

*When  $\ddot{\theta} = 0$  and  $\ddot{z} = 0$ , we can drop the first and last terms and the remaining term is clearly radial. This is the famous centripetal force of rotation in physics- a force that comes about due to the constraint of living on a surface and not due to any other explicit force acting on the particle.*

4. A dying population of insects, evolves in time with the rate of decay given by

$$\frac{dN}{dt} = -(N + cN^2)/\tau.$$

Find the population as a function of time  $t$  and  $N(0)$ , the initial population.

Assuming  $N(0)c = 1$ , show that the population at  $t = \tau$  is  $\frac{1}{2e-1}$  of the initial population.

...[30]

*Solution:* We solve the equation by separation of variables

$$\frac{dN}{N + cN^2} = -\frac{dt}{\tau}$$

so

$$\log\left(\frac{Nc}{N+c}\right) = -\frac{t}{\tau} + \text{const},$$

so the solution is

$$N(t) = \frac{N(0)}{(1 + cN(0))e^{t/\tau} - cN(0)}.$$

We see that at  $t = \tau$  with  $cN(0) = 1$ , the solution gives  $N(\tau)/N(0) = \frac{1}{2e-1}$ , as required.